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The Reversible Computing Question: A Crucial Challenge for Computing

Frontiers of Extreme Computing
Monday, October 24, 2005



Outline of Talk

- Computational energy efficiency (η_{ec}) as the ultimate performance limiter in practical computer systems...
 - Limits on the η_{ec} attainable in conventional machines
- Reversible computing (RC) as the only way out in the long term, after the next decade or two...
 - Review of some basic concepts of reversible logic
- The “Reversible Computing Question:”
 - Can we ever really build *competitive* RC machines?
- Why practical Reversible Computing is difficult...
 - and why it might nevertheless be possible.
- A Call to Action!



Moore's Law and Performance

- Gordon Moore, 1975:

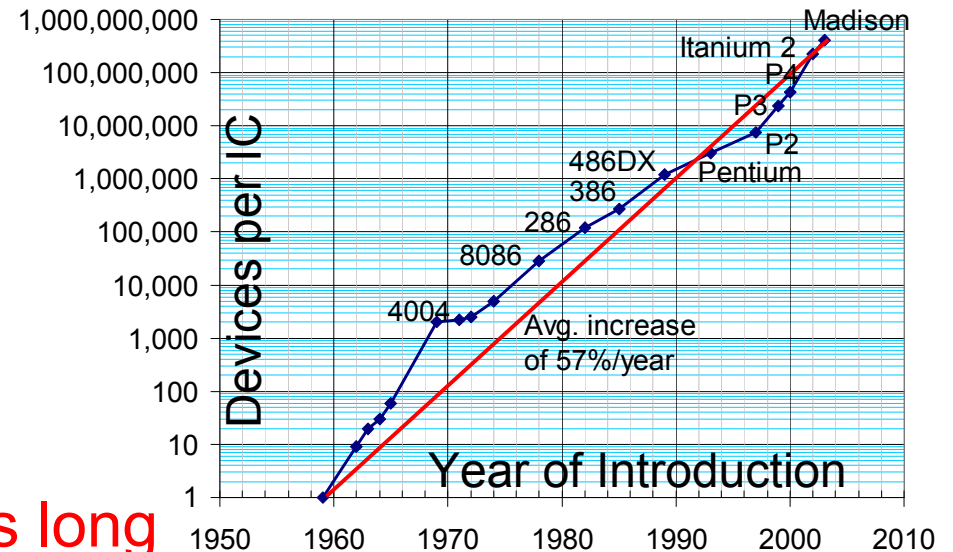
- Devices per IC can be doubled every 18 months
 - Borne out by history, so far...

- Some associated trends:

- Every 3 years: **Devices $\frac{1}{2}$ as long**
- Every 1.5 years: **$\sim\frac{1}{2}$ as much stored energy per bit!**
 - This has enabled us to throw away bits (and their energies) 2× more frequently every 1.5 years, at reasonable power levels!
 - And thereby double processor performance 2× every 1.5 years!

- Increased energy efficiency of computation is a prerequisite for improved raw performance!

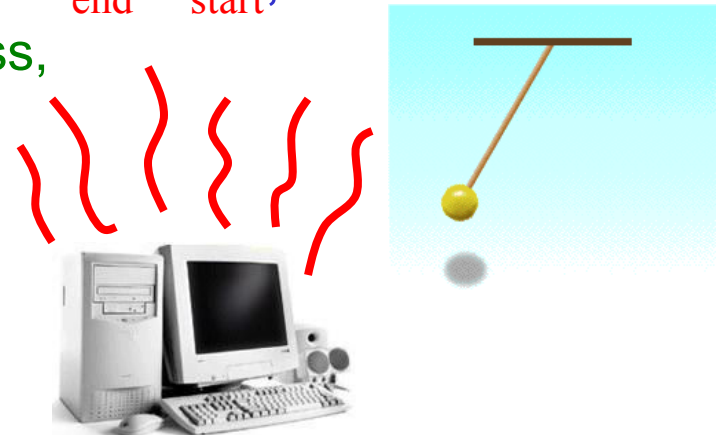
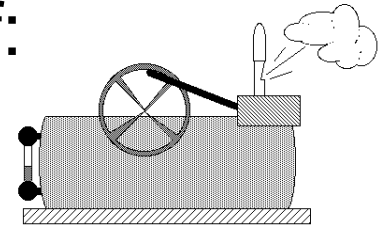
- Given realistic fixed constraints on total power consumption.





Efficiency in General, and Energy Efficiency

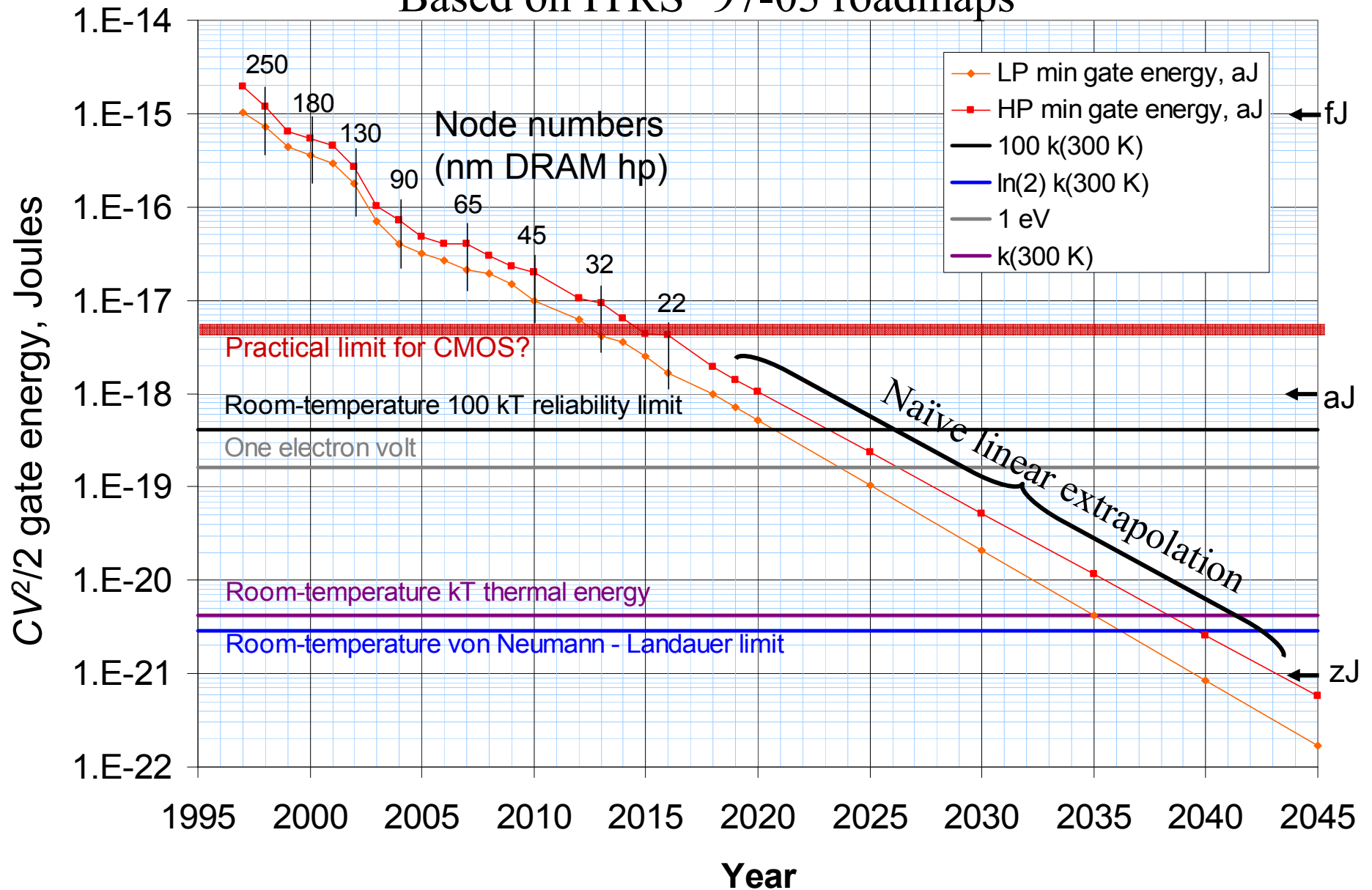
- The *efficiency* η of any process is: $\eta = P/C$
 - Where P = Amount of some valued product produced
 - and C = Amount of some costly resources consumed
- In *energy efficiency* η_e , the cost C measures energy.
- We can talk about the energy efficiency of:
 - A *heat engine*: $\eta_{he} = W/Q$, where:
 - W = work energy output, Q = heat energy input
 - An *energy recovering process* : $\eta_{er} = E_{end}/E_{start}$, where:
 - E_{end} = available energy at end of process,
 - E_{start} = energy input at start of process
 - A *computer*: $\eta_{ec} = N_{ops}/E_{cons}$, where:
 - N_{ops} = # useful operations performed
 - E_{cons} = free-energy consumed





Trend of Minimum Transistor Switching Energy

Based on ITRS '97-03 roadmaps





Some Lower Bounds on Energy Dissipation

- In today's 90 nm VLSI technology, for minimal operations (e.g., conventional switching of a minimum-sized transistor):
 - $E_{\text{diss,op}}$ is on the order of 1 fJ (femtojoule) $\rightarrow \eta_{\text{ec}} \lesssim 10^{15}$ ops/sec/watt.
 - Will be a bit better in coming technologies (65 nm, maybe 45 nm)
- But, conventional digital technologies are subject to several lower bounds on their energy dissipation $E_{\text{diss,op}}$ for digital transitions (logic / storage / communication operations),
 - And thus, corresponding upper bounds on their energy efficiency.
- Some of the known bounds include:
 - Leakage-based limit for high-performance field-effect transistors:
 - Maybe roughly ~ 5 aJ (attojoules) $\rightarrow \eta_{\text{ec}} \lesssim 2 \times 10^{17}$ operations/sec./watt
 - Reliability-based limit for all non-energy-recovering technologies:
 - On the order of 1 eV (electron-volt) $\rightarrow \eta_{\text{ec}} \lesssim 6 \times 10^{18}$ ops./sec/watt
 - von Neumann-Landauer (VNL) bound for all irreversible technologies:
 - Exactly $kT \ln 2 \approx 18$ meV (per bit erasure) $\rightarrow \eta_{\text{ec}} \lesssim 3.5 \times 10^{20}$ ops/sec/watt
 - For systems whose waste heat ultimately winds up in Earth's atmosphere,
 - » i.e., at temperature $T \approx T_{\text{room}} = 300$ K.



Reliability Bound on Logic Signal Energies

- Let E_{sig} denote the *logic signal energy*,
 - The energy *actively involved* (transferred, manipulated) in the process of storing, transmitting, or transforming a bit's worth of digital information.
 - But note that “involved” does not necessarily mean “dissipated!”
- As a result of fundamental thermodynamic considerations, it is required that $E_{\text{sig}} \gtrsim k_B T_{\text{sig}} \ln r$ (with quantum corrections that are small for large r)
 - Where k_B is Boltzmann's constant, 1.38×10^{-12} J/K;
 - and T_{sig} is the temperature in the degrees of freedom carrying the signal;
 - and r is the *reliability factor*, *i.e.*, the improbability of error, $1/p_{\text{err}}$.
- In non-energy-recovering logic technologies (totally dominant today)
 - Basically all of the signal energy is dissipated to heat on each operation.
 - And often additional energy (*e.g.*, short-circuit power) as well.
- In this case, minimum sustainable dissipation is $E_{\text{diss,op}} \gtrsim k_B T_{\text{env}} \ln r$,
 - Where T_{env} is now the temperature of the waste-heat reservoir (environment)
 - Averages around 300 K (room temperature) in Earth's atmosphere
- For a decent r of *e.g.* 2×10^{17} , this minimum is on the order $\sim 40 kT \approx 1$ eV.
 - Therefore, if we want energy efficiency $\eta_{\text{ec}} > \sim 1$ op/eV, we must recover some of the signal energy for later reuse.
 - Rather than dissipating it all to heat with each manipulation of the signal.



The von Neumann-Landauer (VNL) Principle

- First alluded to by John von Neumann in 1949.
 - Developed explicitly by Rolf Landauer of IBM in 1961.
- The principle is a rigorous theorem of physics!
 - It follows from the reversibility of fundamental dynamics.
- A correct statement of the principle is the following:
 - Any process that loses or *obliviously erases* 1 bit of known (correlated) information increases total entropy by at least

$$\Delta S = 1 \text{ bit} = k_B \ln 2,$$

and implies eventual system-level dissipation of at least

$$E_{\text{diss}} = \Delta S \cdot T_{\text{env}} = k_B T_{\text{env}} \ln 2$$

of free energy to the environment as waste heat.

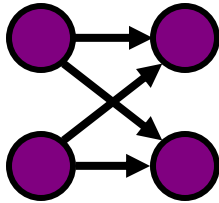
- where $k_B = \text{Log } e = 1.38 \times 10^{-23} \text{ J/K}$ is Boltzmann's constant
- and T_{env} = temperature of the waste-heat reservoir (environment)
 - Not less than about room temperature (300 K) for earthbound computers. \rightarrow implies $E_{\text{diss}} \geq 18 \text{ meV}$.



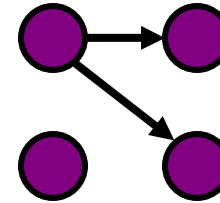
Types of Dynamical Systems

(We're using the physicist's, not the complexity theorist's meaning of "nondeterministic" below)

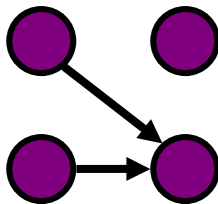
- Nondeterministic, irreversible



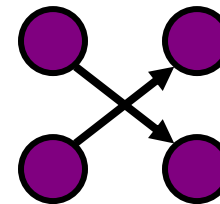
- Nondeterministic, reversible



- Deterministic, irreversible



- Deterministic, reversible



WE
ARE
HERE



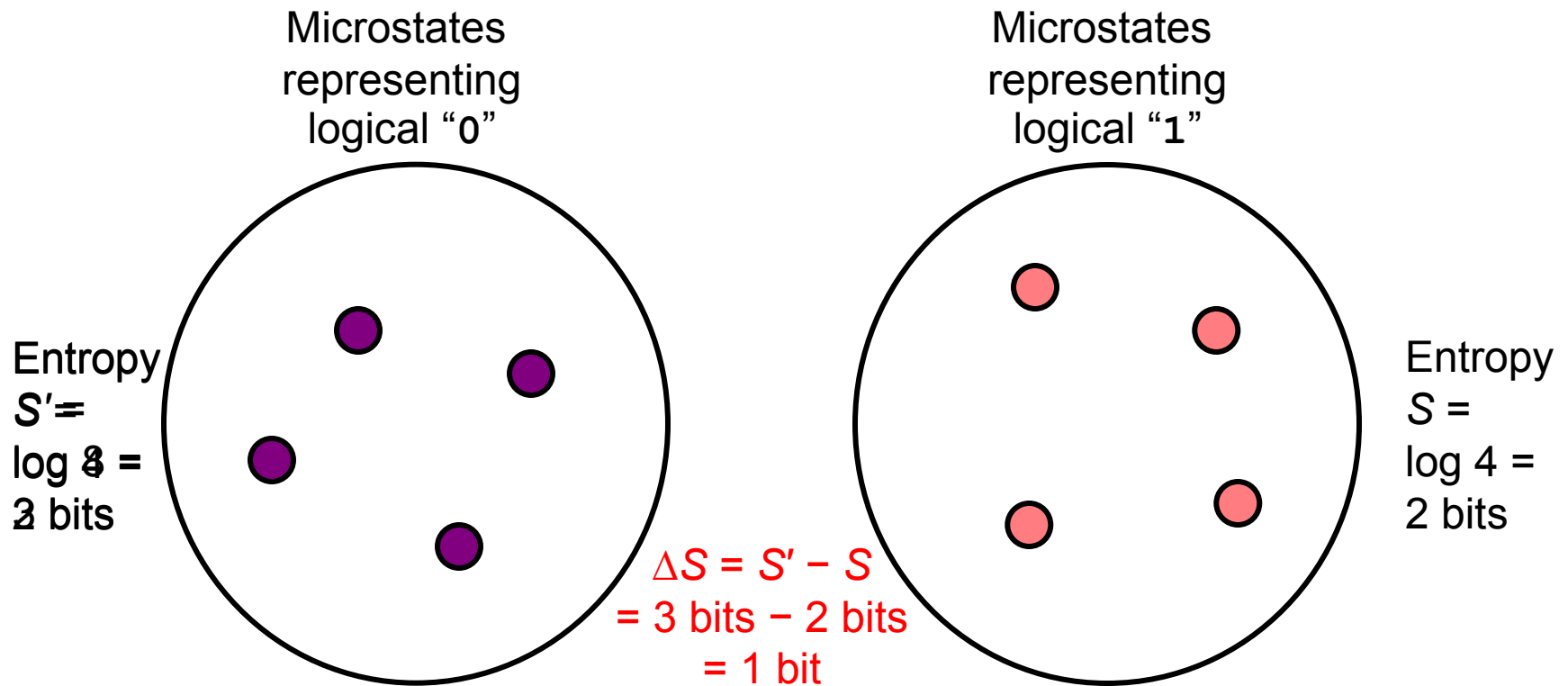
Physics is Reversible

- All the successful models of fundamental physics are expressible in the *Hamiltonian* formalism.
 - Including: Classical mechanics, quantum mechanics, special and general relativity, quantum field theories.
 - The latter two (GR & QFT) are backed up by enormous, overwhelming mountains of evidence confirming their predictions!
 - 11 decimal places of precision so far! And, no contradicting evidence.
- In Hamiltonian systems, the dynamical state $x(t)$ obeys a differential equation that's first-order in time,
$$dx/dt = g(x) \quad (\text{where } g \text{ is some function})$$
 - This immediately implies determinism of the dynamics.
- And, since the time differential dt can be taken to be negative, the formalism also implies reversibility.
 - Thus, dynamical reversibility is one of the most firmly-established, inviolable facts of fundamental physics.



Illustration of VNL Principle

- Either digital state is initially encoded by any of N possible physical microstates
 - Illustrated as 4 in this simple example (the real number would usually be much larger)
 - Initial entropy $S = \log[\#\text{microstates}] = \log 4 = 2$ bits.
- Reversibility of physics ensures “bit erasure” operation can’t possibly merge two microstates, so it must double the possible microstates in the digital state!
 - Entropy $S = \log[\#\text{microstates}]$ increases by $\log 2 = 1$ bit = $(\log e)(\ln 2) = k_B \ln 2$.
 - To prevent entropy from accumulating locally, it must be expelled into the environment.





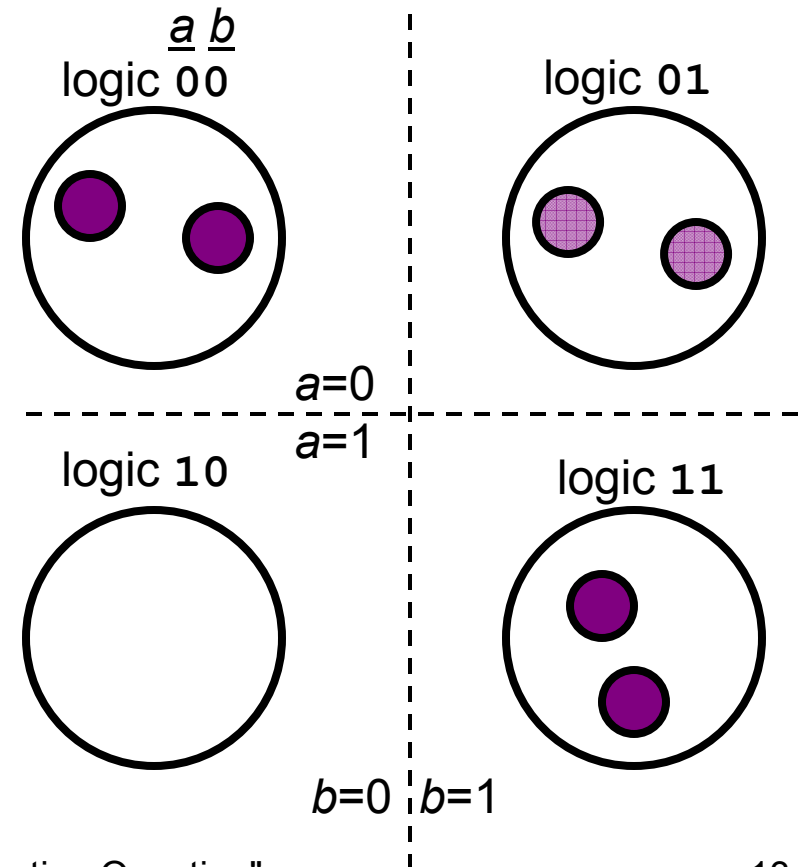
Reversible Computing

- The basic idea is simply this:
 - *Don't discard information* when performing logic / storage / communication operations!
 - Instead, just reversibly (invertibly) transform it, in place!
- When reversible digital operations are implemented using well-designed energy-recovering circuitry,
 - This can result in local energy dissipation $E_{\text{diss}} \ll E_{\text{sig}}$,
 - this has already been empirically demonstrated by many groups.
 - and (in principle) total energy dissipation $E_{\text{diss}} \ll kT \ln 2$.
 - This is easily shown in theory & simulations,
 - but we are not yet to the point of demonstrating such low levels of total dissipation empirically in a physical experiment.
 - Achieving this goal will require very careful design,
 - and verifying it requires very sensitive measurement equipment.



How Reversible Logic Avoids the von Neumann-Landauer Bound

- We arrange our logical manipulations to never attempt to merge two distinct digital states,
 - but only to reversibly transform them from one state to another!
- *E.g.*, illustrated is a reversible operation “**cCLR**” (controlled clear)
 - Non-oblivious “erasure”
 - It and its inverse (**cSET**) enable arbitrary logic!

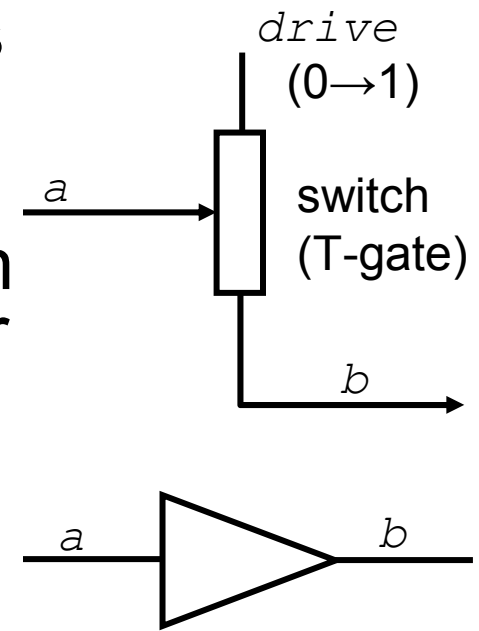




Notations for a Useful Primitive: Controlled-SET or **cSET** (a, b)

- **Function:** If $a=1$, then set $b:=1$.
 - *Conditionally* reversible, if the precondition $ab=0$ is met.
 - Note it's 1-to-1 on the subset of states used
 - Sufficient to avoid Landauer's principle!
- We can implement **cSET** in dual-rail CMOS with a pair of transmission gates
 - Each needs just 2 transistors,
 - plus one controlling "drive" signal
- This 2-bit semi-reversible operation with its inverse **cCLR** form a universal set for reversible (and irreversible) logic!
 - If we compose them in special ways.
 - And include latches for sequential logic.

a	b	a'	b'
0	0	0	0
0	1	0	1
1	0	1	1





Example Implementation of a Reversible CMOS “cSET/cCLR” gate

- Formal semantics for a **controlled-SET** (cSET) operation:

```

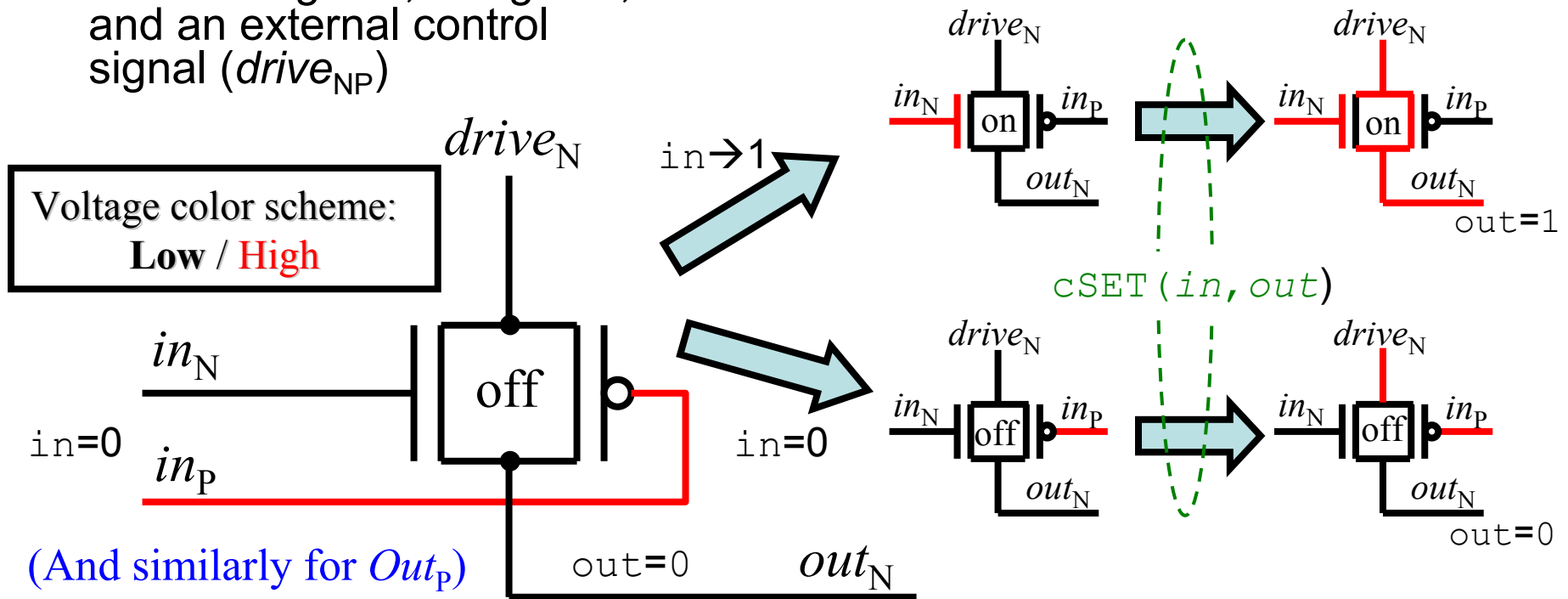
cSET(in, out) ::=
  [~(in & out)]
  if in then out:0->1
  [~in | out]
  
```

Precondition: If $in=1$ we must have $out=0$ initially.

Action: If $in=1$, then take out from 0 to 1.

Postcondition: If $in=1$ then $out=1$ afterwards.

- The below implementation uses dual-rail signals, 2 T-gates, and an external control signal ($drive_{NP}$)

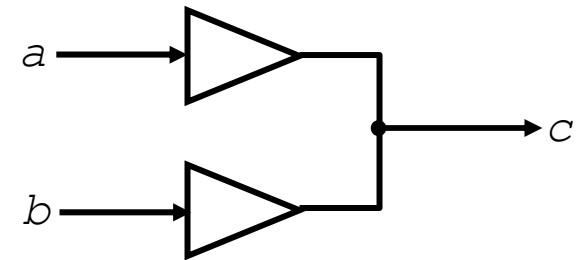




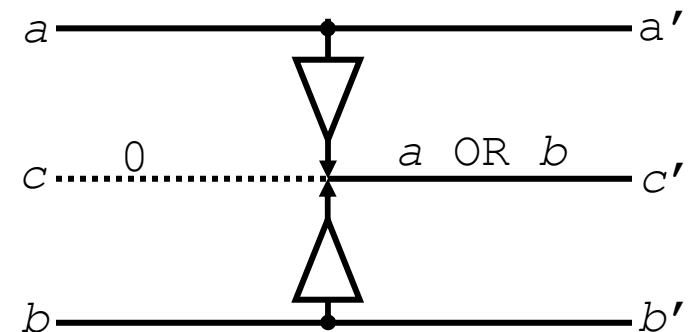
Reversible OR (\mathbf{rOR}) from \mathbf{cSET}

- **Semantics:** $\mathbf{rOR}(a, b) ::= \text{if } a|b, c:=1.$
 - Set $c:=1$, on the condition that either a or b is 1.
 - Reversible under precondition that initially $a|b \rightarrow \sim c.$
- Two parallel \mathbf{cSET} s simultaneously driving a shared output bus implements the \mathbf{rOR} operation!
 - This type of gate composition was not traditionally considered.
- Similarly one can do \mathbf{rAND} , and reversible versions of all operations.
 - Logic synthesis with these is extremely straightforward...

Hardware diagram



Spacetime diagram

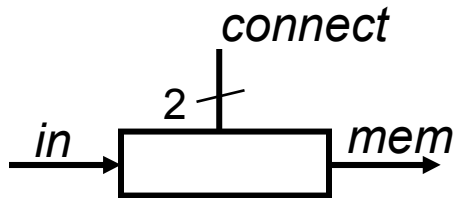




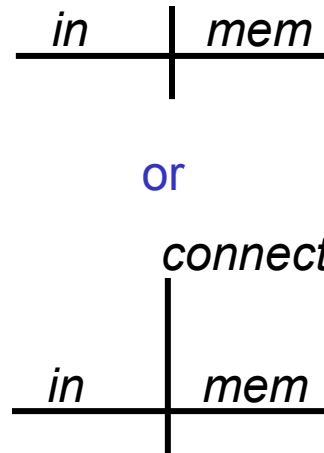
CMOS Gate Implementing rLatch / rUnLatch

- Symmetric Reversible Latch

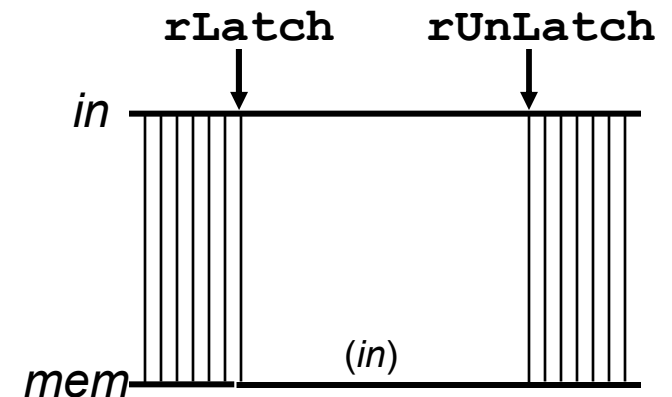
Implementation



Concise Icon



Spacetime Diagram



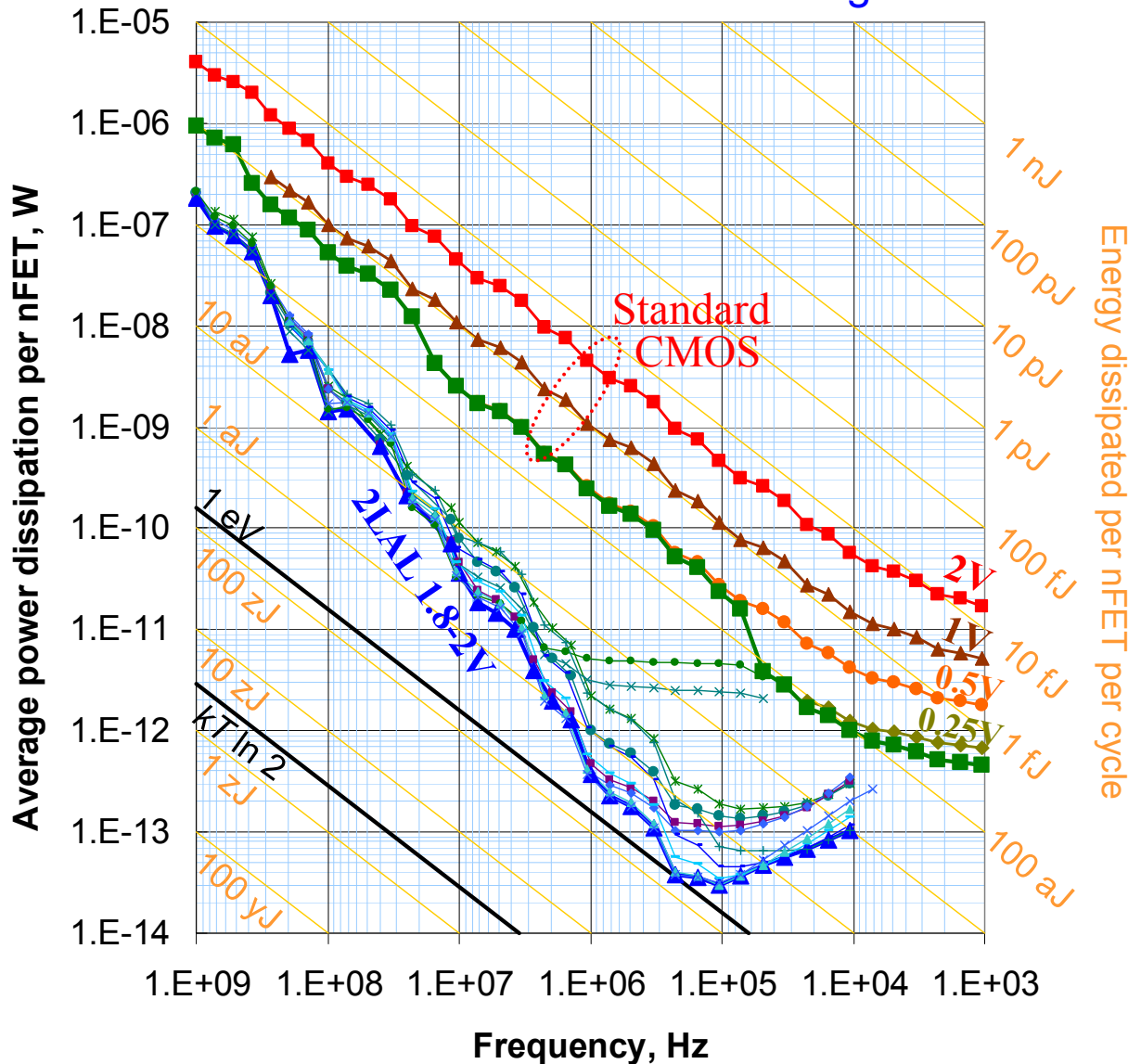
- The hardware is just a CMOS transmission gate again
 - This time controlled by a clock, with the data signal driving
- Concise, symmetric hardware icon – Just a short orthogonal line
- In spacetime diagram, thin strapping lines denote inter-node connection.



Cadence Simulation Results

Power vs. freq., TSMC 0.18, Std. CMOS vs. 2LAL

2LAL = Two-level adiabatic logic

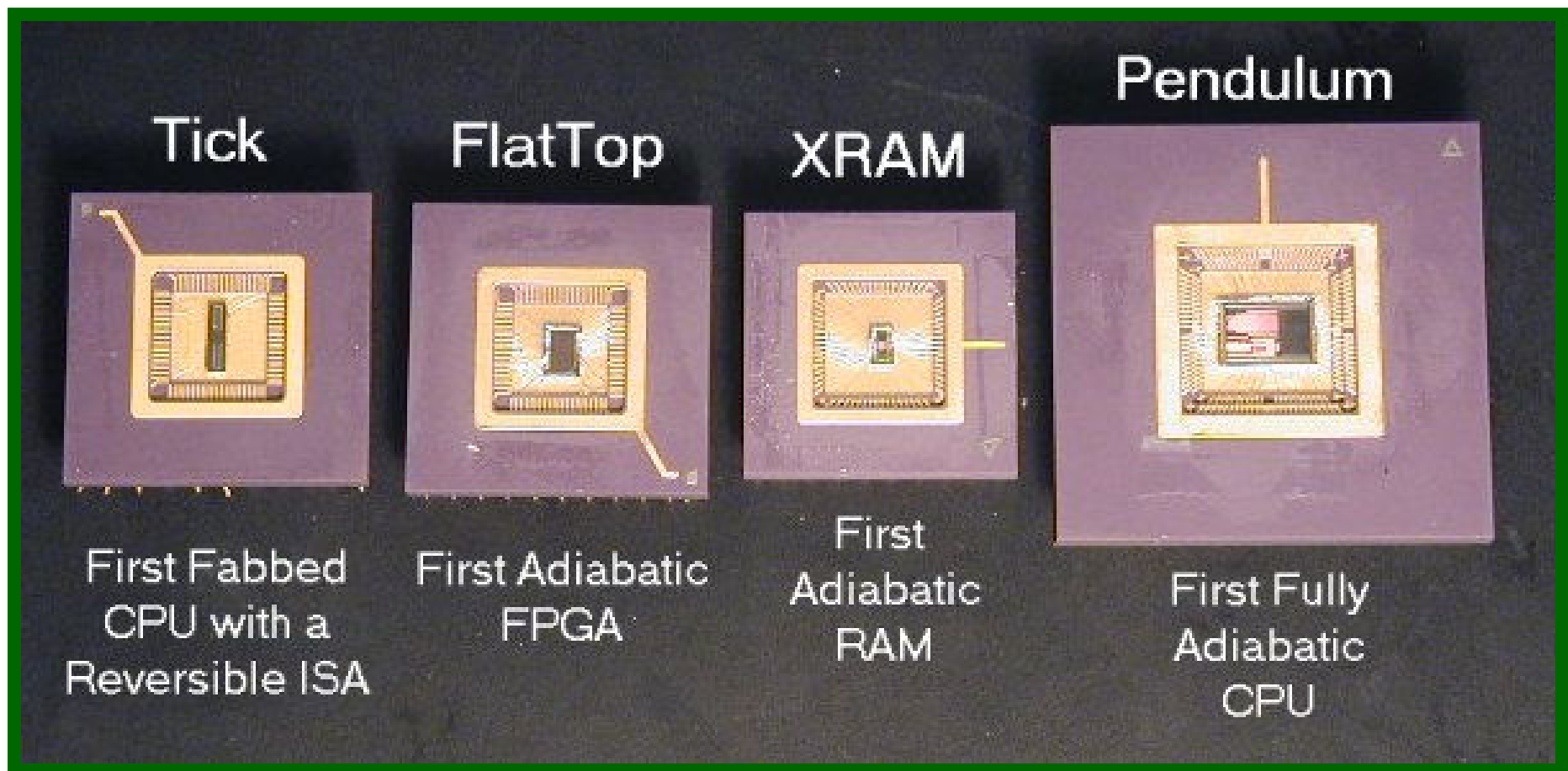


- Graph shows power dissipation vs. frequency
 - in 8-stage shift register.
- At moderate frequencies (1 MHz),
 - Reversible uses < 1/100th the power of irreversible!
- At ultra-low power (1 pW/transistor)
 - Reversible is 100× faster than irreversible!
- Minimum energy dissipation < 1 eV!
 - 500× lower than best irreversible!
 - 500× higher computational energy efficiency!
- Energy transferred is still ~10 fJ (~100 keV)
 - So, energy recovery efficiency is 99.999%!
 - Not including losses in power supply, though



Reversible and/or Adiabatic VLSI Chips Designed @ MIT, 1996-1999

By Frank and other then-students in the MIT Reversible Computing group,
under CS/AI lab members Tom Knight and Norm Margolus.





A Few Highlights Of Reversible Computing History

- Charles Bennett @ IBM, 1973-1989:
 - Reversible Turing machines & emulation algorithms
 - Can emulate irreversible machines on reversible architectures.
 - But, the emulation introduces some inefficiencies
 - Early chemical & Brownian-motion implementation concepts.
- Ed Fredkin and Tom Toffoli's group @ MIT, late 1970's/early 1980's
 - Reversible logic gates and networks (space/time diagrams)
 - Ballistic mechanical and adiabatic circuit implementation proposals
- Paul Benioff, Richard Feynman, Norm Margolus, mid-1980s
 - Abstract quantum-mechanical models of “classical” reversible computers.
 - The field of quantum computing eventually emerged from this line of work
- Several groups @ Caltech, ISI, Amherst, Xerox, MIT, mid '80s-mid '90s:
 - Concepts for & implementations of “adiabatic circuits” in VLSI technology
 - Small explosion of adiabatic circuit literature since then!
- Mid 1990s-today:
 - Better understanding of overheads, tradeoffs, asymptotic scaling
 - A few groups have begun development of post-CMOS implementations
 - Most notably, the Quantum-dot Cellular Automata group at Notre Dame



Reversibility and Reliability

- **A widespread claim:** “Future low-level digital devices will necessarily be highly unreliable.”
 - This comes from questionable lines of reasoning, such as:
 - Faster → more energy efficient ~~→~~ lower bit energies → high rate of bit errors from thermal noise
 - However, this scaling strategy doesn't work, because:
 - High rate of thermal errors → high power dissipation from error correction → less energy efficient → ultimately slower!
- But in contrast, using reversible computing, in principle, we can achieve arbitrarily high energy efficiency and arbitrarily high reliability!
 - The key is to keep bit energies reasonably high!
 - Improve efficiency by recovering more and more of the bit energy...



Minimizing Energy Dissipation Due to Thermal Errors

- Let $p_{\text{err}} = 1/r$ be the bit-error probability per operation.
 - Where r quantifies the “reliability level.”
 - And $p_{\text{ok}} = 1 - p_{\text{err}}$ is the probability the bit is correct
- The minimum entropy increase ΔS per op due to error occurrence is given by the (binary) Shannon entropy of the bit-value after the operation:

$$H(p_{\text{err}}) = p_{\text{err}} \log p_{\text{err}}^{-1} + p_{\text{ok}} \log p_{\text{ok}}^{-1}.$$

- For $r \gg 1$ (i.e., as $r \rightarrow \infty$), this increase approaches 0:

$$\Delta S = H(p_{\text{err}}) \approx p_{\text{err}} \log p_{\text{err}}^{-1} = (\log r)/r \rightarrow 0$$

- Thus, the required energy dissipation per op also approaches 0:

$$E_{\text{diss}} = T\Delta S \approx (kT \ln r)/r \rightarrow 0$$

- Could get the same result by assuming the signal energy $E_{\text{sig}} = kT \ln r$ required for reliability level r is dissipated each time an error occurs:

$$E_{\text{diss}} = p_{\text{err}} E_{\text{sig}} = p_{\text{err}} (kT \ln r) = (kT \ln r)/r \rightarrow 0 \text{ as } r \rightarrow \infty.$$

- Further, note that as $r \rightarrow \infty$, the required signal energy grows slowly...
 - Only logarithmically in the reliability, i.e., $E_{\text{sig}} = \Theta(\log r)$.



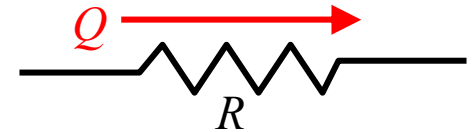
Some Device-Level Requirements for Reversible Computing

- A good reversible device technology should have:
 - Low manufacturing cost ϕ_d per device
 - Important for good overall (system-level) cost-efficiency
 - Low rate of static “standby” power dissipation P_{sby} due to energy leakage, thermally-induced errors, etc.
 - Required for energy-efficient storage especially (but also in logic)
 - Low *energy coefficient* $c_{Et} = E_{diss} \cdot t_{tr}$ (energy dissipated per operation, times transition time) for adiabatic transitions.
 - Implies that we can achieve a high operating frequency (and thus good cost-performance) at a given level of energy efficiency.
 - High maximum available transition frequency f_{max} .
 - Especially important for those applications in which the latency of serial threads of computation dominates the total operating costs



Energy & Entropy Coefficients in Electronics

- For a transition involving the adiabatic transfer of an amount Q of charge along a path with resistance R :



- The raw (local) energy coefficient is

$$c_{\text{Et}} = E_{\text{diss}} t = P_{\text{diss}} t^2 = IV t^2 = I^2 R t^2 = Q^2 R.$$

- Where V is the voltage drop along the path.

- The entropy coefficient is $c_{\text{St}} = Q^2 R / T_{\text{path}}$.

- where T_{path} is the local thermodynamic temperature in the path.

- The effective (global) energy coefficient is

$$c_{\text{Et,eff}} = Q^2 R (T_{\text{env}} / T_{\text{path}}).$$

- Note that we pay a penalty for low-T operation!



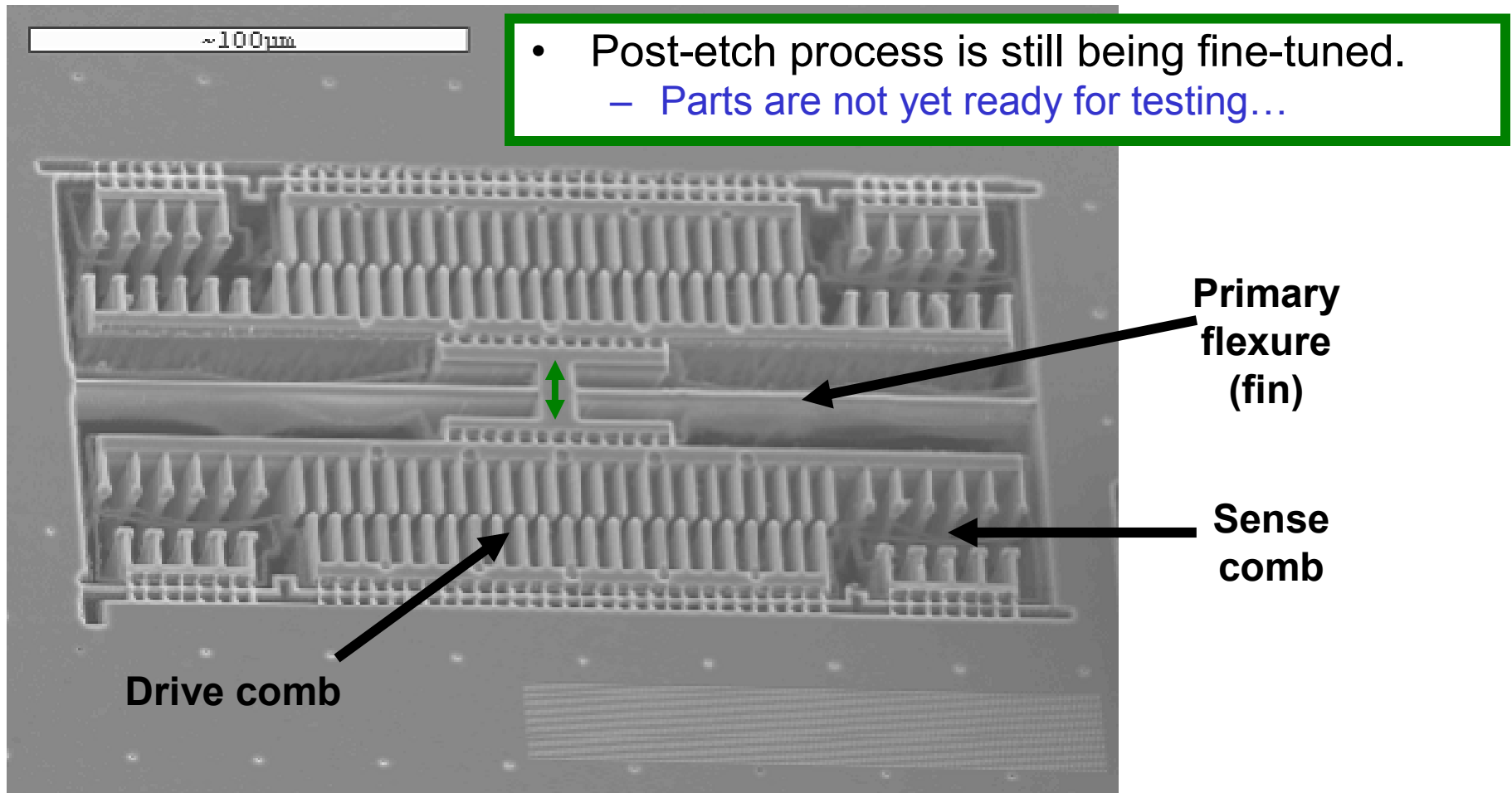
Requirements for Energy-Recovering Clock/Power Supplies

- All of the known reversible computing schemes invoke a periodic global signal that synchronizes and drives adiabatic transitions in the logic.
 - For good system-level energy efficiency, this signal must oscillate resonantly and near-ballistically, with a high effective quality factor.
- Several factors make the design of a resonant clock distributor that has satisfactorily high efficiency quite difficult:
 - Any uncompensated back-action of logic on resonator
 - In some resonators, Q factor may scale unfavorably with size
 - Excess stored energy in resonator may hurt effective quality factor
- There's no reason to think that it's impossible to do it...
 - But it is definitely a nontrivial hurdle, that we reversible computing researchers need to face up to, pretty urgently...
 - If we want to make reversible computing practical in time to avoid an extended period of stagnation in computer performance growth.



MEMS Quasi-Trapezoidal Resonator: 1st Fabbed Prototype

(Funding source: SRC CSR program)



(PATENT PENDING, UNIVERSITY OF FLORIDA)



General Reasons Why Practical Reversible Computing is Difficult

- Complex physical systems typically include *many* naturally occurring channels & mechanisms for energy dissipation.
 - Electromagnetic emission, phonon excitation, scattering, *etc.*
 - All must be delicately blocked to truly approach zero dissipation.
- We really must direct & keep track of where all (or nearly all) of the system's active energy is going at all times!
 - Accurately control/track the system's trajectory in configuration space.
 - Requires great care in design, & great precision in modeling.
- The physical architecture of the system is tightly constrained by the requirement for (near-) reversibility of the logic.
 - Gate-level synchrony, careful load balancing, elimination of unwanted reflections from impedance non-uniformities, *etc.*
 - Reversible logic, functional units, HW architectures & SW algorithms.
- Reversible logic itself introduces substantial (polynomial) space-time complexity overheads.
 - These bite a large chunk off of its energy-efficiency benefits.
 - This overhead appears to be inevitable in general-purpose apps.



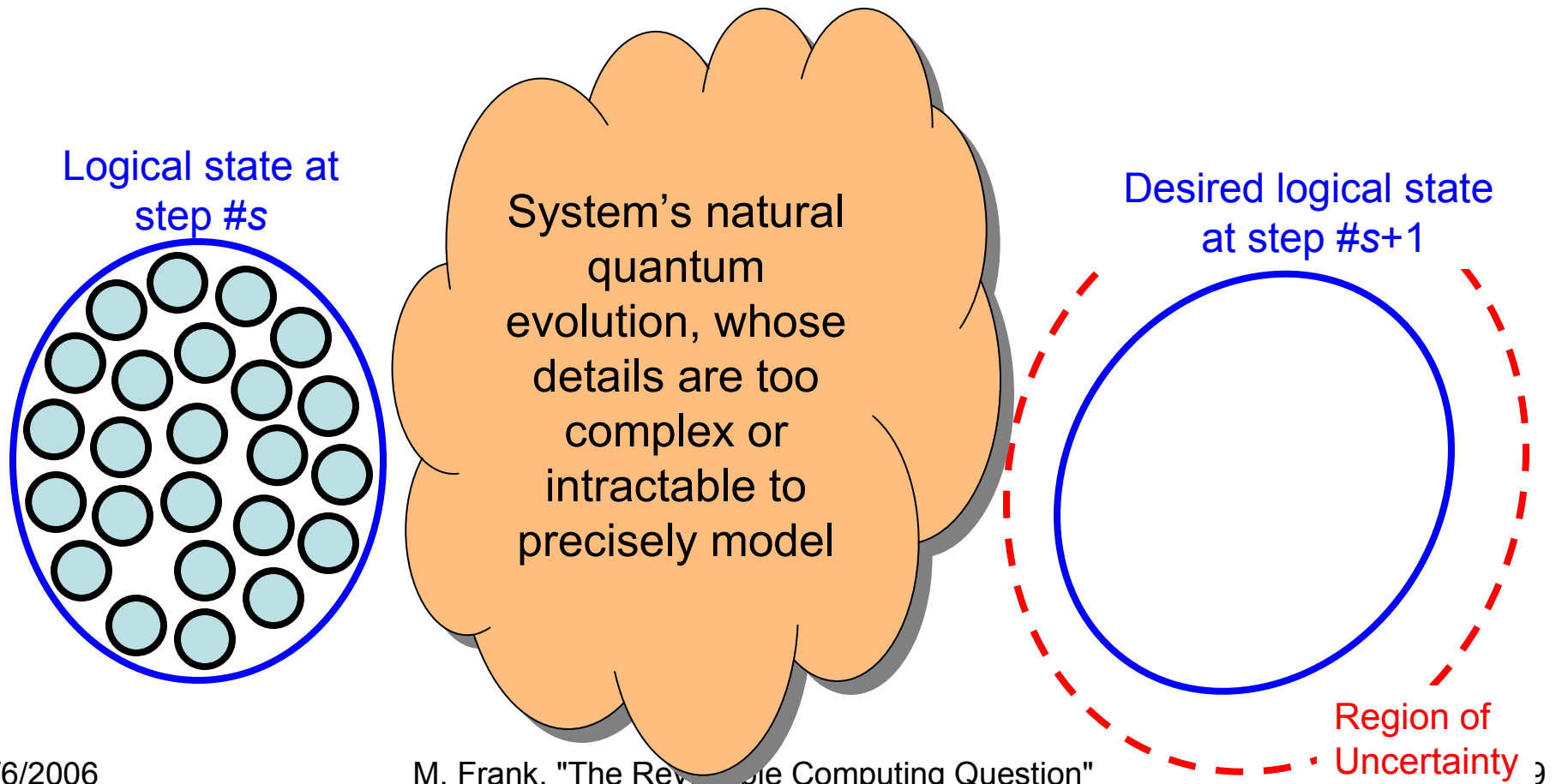
Why Reversible Computing Might Still Be Possible, Eventually...

- Fundamentally, we know from quantum theory that physical systems intrinsically evolve with no inherent entropy increase.
 - A precisely characterized unitary evolution $\rho(t) = U(t)\rho(0)$ conserves the entropy $S(\rho)$ of any initial mixed state ρ .
- Thus, all “apparent” entropy increase ultimately arises from:
 - Imprecision in our knowledge of the fundamental physical laws (U).
 - Physical modeling techniques that (for practical reasons) explicitly neglect some of the information that we could infer about the state.
 - E.g., State vector projection, reduced density matrices, decoherence.
- To build systems with arbitrarily slow entropy increase, “just:”
 - Refine our knowledge of physical laws (values of constants, etc.) to ever more precision.
 - Develop ever more accurate, less approximate techniques for analytically/numerically modeling the time evolution of larger systems.
 - Learn how to design & construct increasingly complex systems whose engineered built-in dynamics is increasingly useful & powerful,
 - while still remaining feasible to model and track accurately.



One Big Reason for Optimism

- For a machine to have a high degree of *classical* reversibility *doesn't* appear to require that we maintain global phase coherence, or track the entire detailed evolution of all the quantum microstates...
 - It only requires that the rate of inflation of phase space volume is not too fast, and that most states end up *somewhere* in the desired region
 - Knowing which states go where within the desired region is not important





A Call to Action

- The world of computing is threatened by permanent performance-per-power stagnation in 1-2 decades...
 - We really should try hard to avoid this, if at all possible!
 - A wide variety of very important applications will be impacted.
- Many more of the nation's (and the world's) top physicists and computer scientists must be recruited,
 - to tackle the great "Reversible Computing Challenge."
- **Urgently needed:** A major new funding program; a "Manhattan Project" for energy-efficient computing!
 - **Mission:** Demonstrate computing beyond the von Neumann-Landauer limit in a practical, scalable machine!
 - Or, if it really can't be done for some reason, find a completely rock-solid proof from fundamental physics showing why.



Conclusions

- Practical reversible computing will become a necessity within our lifetimes,
 - if we want substantial progress in computing performance/power beyond the next 1-2 decades.
- Much progress in our understanding of RC has been made in the past three decades...
 - But much important work still remains to be done.
- I encourage my audience to help me urge the nation's best thinkers to join the cause of finally answering the Reversible Computing Question, once and for all.